

New York University Tandon School of Engineering
Computer Science and Engineering
CS-GY 6763: Midterm Practice.

Logistics

- Exam will be held in class on **Wednesday, 10/26** starting at 11:05pm. Please arrive on time!
- Lucas will give a lecture for the second half of class after a short break.
- You will have **1 hour, 15 minutes** to answer a variety of short answer and longer form questions.
- You can bring a one page sheet of paper (two-sided if you want) with notes, theorems, etc. written down for reference.
- I will be in the room to answer any questions.

Concepts to Know

Random variables and concentration.

- Linearity of expectation and variance.
- Indicator random variables and how to use them.
- Markov's inequality, Chebyshev's inequality (ideally should know from memory so you can apply quickly).
- Union bound (should know from memory).
- Chernoff and Bernstein bounds (don't need to memorize the exact bounds, but can apply if given).
- General idea of law of large numbers and central limit theorem.
- The probability that a normal random variables $\mathcal{N}(0, \sigma^2)$ falls further than $k\sigma$ away from its expectation is $\leq O(e^{-k^2/2})$.

Hashing, Dimensionality Reduction, High Dimensional Vectors

- Random hash functions.
- Random hashing for frequency estimation.
- Random hashing for distinct elements estimation.
- MinHash for Jaccard similarity estimation.
- Locality sensitive hash functions.
- MinHash and SimHash for Jaccard Similarity and Cosine Similarity.
- Adjusting false positive rate and false negative rate in an LSH scheme.
- Statement of Johnson-Lindenstrauss lemma (know from memory).
- Statement of *distributional* JL lemma and how it can be used to prove JL.

High dimensional geometry

- How to draw a random unit vector from the sphere in d dimensions (draw \mathbf{x} with all entries i.i.d. $\mathcal{N}(0, 1)$ and normalize it).
- How does $\|x - y\|_2^2$ relate to $\langle x, y \rangle$ if x and y are unit vectors?
- How many mutually orthogonal unit vectors are there in d dimensions?
- There are $2^{\theta(\epsilon^2 d)}$ nearly orthogonal unit vectors in d dimensions (with $\langle x, y \rangle \leq \epsilon$). Know roughly how prove this fact using the *probabilistic method*, which required a an exponential *concentration inequality* + *union bound*.
- Know how to prove that all but an $2^{\theta(-\epsilon d)}$ fraction of a balls volume in d dimensions lies in a spherical shell of width ϵ near its surface.
- The surface area/volume ratio *increases* in high dimensions.
- The cube volume/ball volume ratio *increases* in high dimensions.

Convex optimization

- Definition(s) of convex function.
- Definition of convex set.
- Gradient descent basic update rule.
- Definitions of G -Lipschitz, β -smooth, α -strongly convex. Know the first order definition for high-dimensional functions. The second order definition you only need to know for low-dimensional functions. I.e. a twice differentiable function $f : \mathbb{R} \rightarrow \mathbb{R}$ is β -smooth, α -strongly convex if for all x , $\alpha \leq f''(x) \leq \beta$. I won't test on Hessians.
- Definition of condition number.
- How much time does it take to multiply an $n \times d$ matrix by a $d \times m$ matrix?
- Be able to compute gradients of basic functions from $\mathbb{R}^d \rightarrow \mathbb{R}$.
- Definition(s) of convex function.

Practice Problems

Random variables and concentration.

1. Show that for any random variable X , $\mathbb{E}[X^2] \geq \mathbb{E}[X]^2$.
2. Show that for independent X and Y with $\mathbb{E}[X] = \mathbb{E}[Y] = 0$, $\text{var}[X \cdot Y] = \text{var}[X] \cdot \text{var}[Y]$.
3. Given a random variable X , can we conclude that $\mathbb{E}[1/X] = 1/\mathbb{E}[X]$? If so, prove this. If not, give an example where the equality does not hold.
4. Indicate whether each of the following statements is **always** true, **sometimes** true, or **never** true. Provide a short justification for your choice.
 - (a) $\Pr[X = s \text{ and } Y = t] > \Pr[X = s]$. ALWAYS SOMETIMES NEVER
 - (b) $\Pr[X = s \text{ or } Y = t] \leq \Pr[X = s] + \Pr[Y = t]$. ALWAYS SOMETIMES NEVER
 - (c) $\Pr[X = s \text{ and } Y = t] = \Pr[X = s] \cdot \Pr[Y = t]$. ALWAYS SOMETIMES NEVER
5. Assume there are 1000 registered users on your site u_1, \dots, u_{1000} , and in a given day, each user visits the site with some probability p_i . The event that any user visits the site is independent of what the other users do. Assume that $\sum_{i=1}^{1000} p_i = 500$.

- (a) Let X be the number of users that visit the site on the given day. What is $E[X]$?
 - (b) Apply a Chernoff bound to show that $Pr[X \geq 600] \leq .01$.
 - (c) Apply Markov's inequality and Chebyshev's inequality to bound the same probability. How do they compare?
6. Give an example of a random variable and a deviation t where Markov's inequality gives a tighter upper bound than Chebyshev's inequality.

Hashing, Dimensionality Reduction, High Dimensional Vectors

1. Suppose there is some unknown vector $\boldsymbol{\mu} \in \mathbb{R}^d$. We receive noise perturbed random samples of the form $\mathbf{Y}_1 = \boldsymbol{\mu} + \mathbf{X}_1, \dots, \mathbf{Y}_k = \boldsymbol{\mu} + \mathbf{X}_k$ where each \mathbf{X}_i is a random vector with each of its entries distributed as an independent random normal $\mathcal{N}(0, 1)$. From our samples $\mathbf{Y}_1, \dots, \mathbf{Y}_k$ we hope to estimate $\boldsymbol{\mu}$ by $\tilde{\boldsymbol{\mu}} = \frac{1}{k} \sum_{i=1}^k \mathbf{Y}_i$.
 - (a) How many samples k do we require so that $\max_{i=1, \dots, d} |\mu_i - \tilde{\mu}_i| \leq \epsilon$ with probability 9/10?
 - (b) How many samples k do we require so that $\|\boldsymbol{\mu} - \tilde{\boldsymbol{\mu}}\|_2 \leq \epsilon$ with probability 9/10?
2. Let $\mathbf{\Pi}$ be a random Johnson-Lindenstrauss matrix (e.g. scaled random Gaussians) with $O(\log(1/\delta)/\epsilon^2)$ rows. Prove that with probability $(1 - \delta)$,

$$\min_{\mathbf{x}} \|\mathbf{\Pi A x} - \mathbf{\Pi b}\|_2^2 \leq (1 + \epsilon) \min_{\mathbf{x}} \|\mathbf{A x} - \mathbf{b}\|_2^2$$

Convex optimization

From *Convex Optimization* book (https://web.stanford.edu/~boyd/cvxbook/bv_cvxbook.pdf):

- **Exercises:** 3.7, 3.10, 3.11 (first part), 3.21 (lots of other problems if you want more practice, but many are on the harder side)
1. Let $f_1(x), \dots, f_n(x)$ be β -smooth convex functions and let $g(x) = \frac{1}{n} \sum_{i=1}^n f_i(x)$ be their average. Show that g is β -smooth.
 2. Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a β -smooth, α -strongly convex function. Let $g(x) = f(c \cdot x)$ for some constant $0 < c < 1$. How does g 's smoothness and strong convexity compare to that of f ? How about g 's condition number?
 3. Let $f(x) = x^4$. Is f G -Lipschitz for finite G ? Is f β -smooth for finite B ?